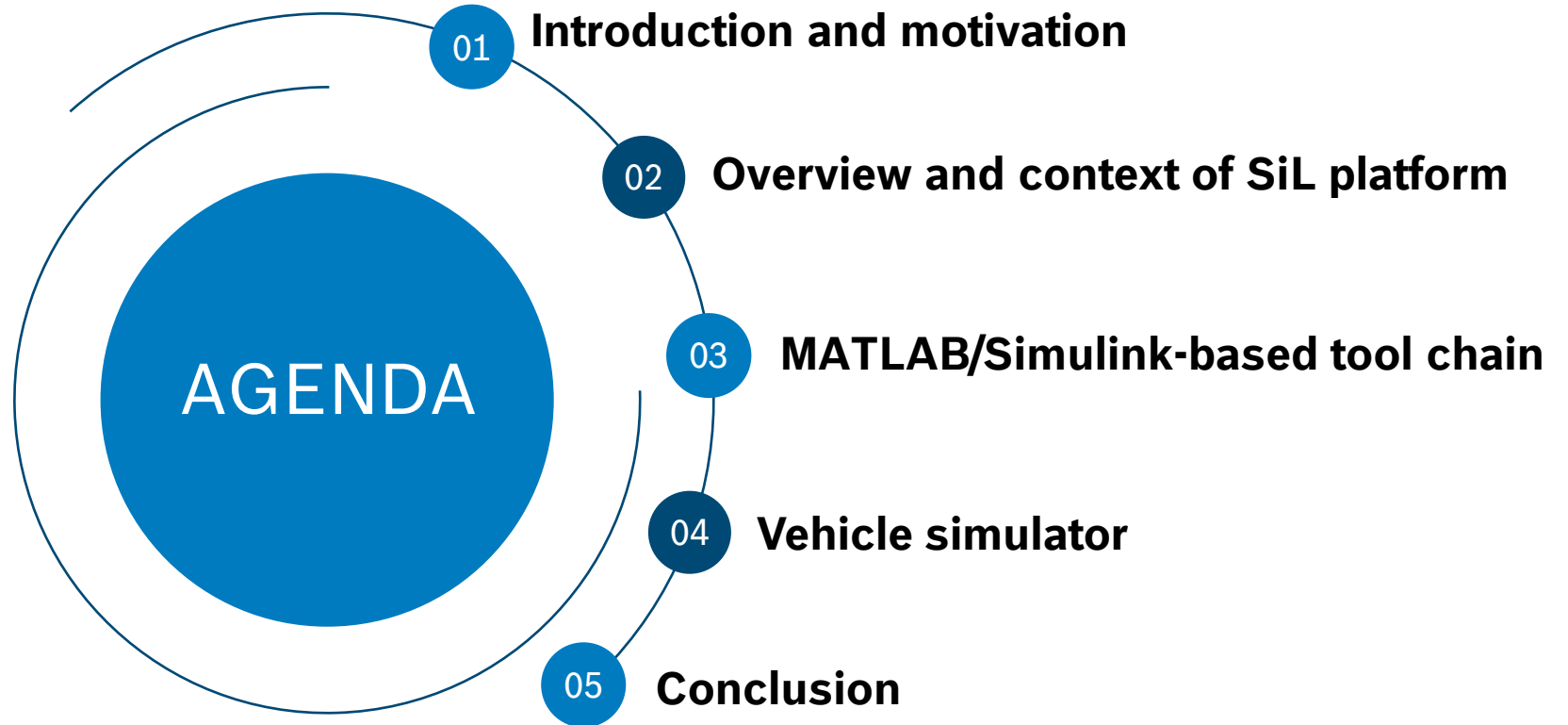


Bosch Engineering GmbH
Dr.-Ing. Irina Kaiser

**MATLAB/Simulink-based
cross-domain simulation platform for
Advanced driver assistance systems (ADAS)**

MATLAB/Simulink-based Cross-Domain SiL platform

Agenda



MATLAB/Simulink-based Cross-Domain SiL platform

Introduction and motivation

Project challenges of today ...



Calibration and prototype development need vehicle



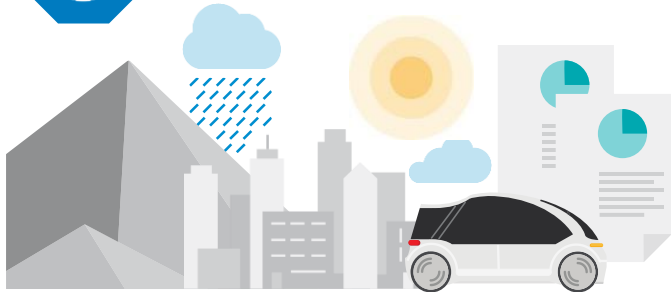
An increase in testing leads to an exponential increase in costs



Some safety critical and complex tests are not possible or need special equipment



Iterations and long release cycles



Bosch Engineering provides the solution!

Simulation approach that speeds up the system engineering and prototype development by tests in virtual validation and verification platform.



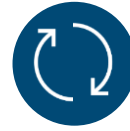
Your benefits with ADAS simulation ...



Use your physical resources only for required final verification and calibration



Continuous testing, low-risk execution of extreme tests



Reduce of costs for development and testing: reduction of iterations, release cycles



Virtual demonstration of features



BOSCH

MATLAB/Simulink-based Cross-Domain SiL platform

Introduction and motivation: Use Cases

Development of virtual ADAS ECUs and delivery to customer



24/7 Automation

Development, first application, verification and validation of ECU software in virtual simulation environment



Software calibration in virtual environment

Virtual prototype development



Highly reproducible testing environment

Simulation services (e.g. virtual join test, SiL qualification, test analysis)

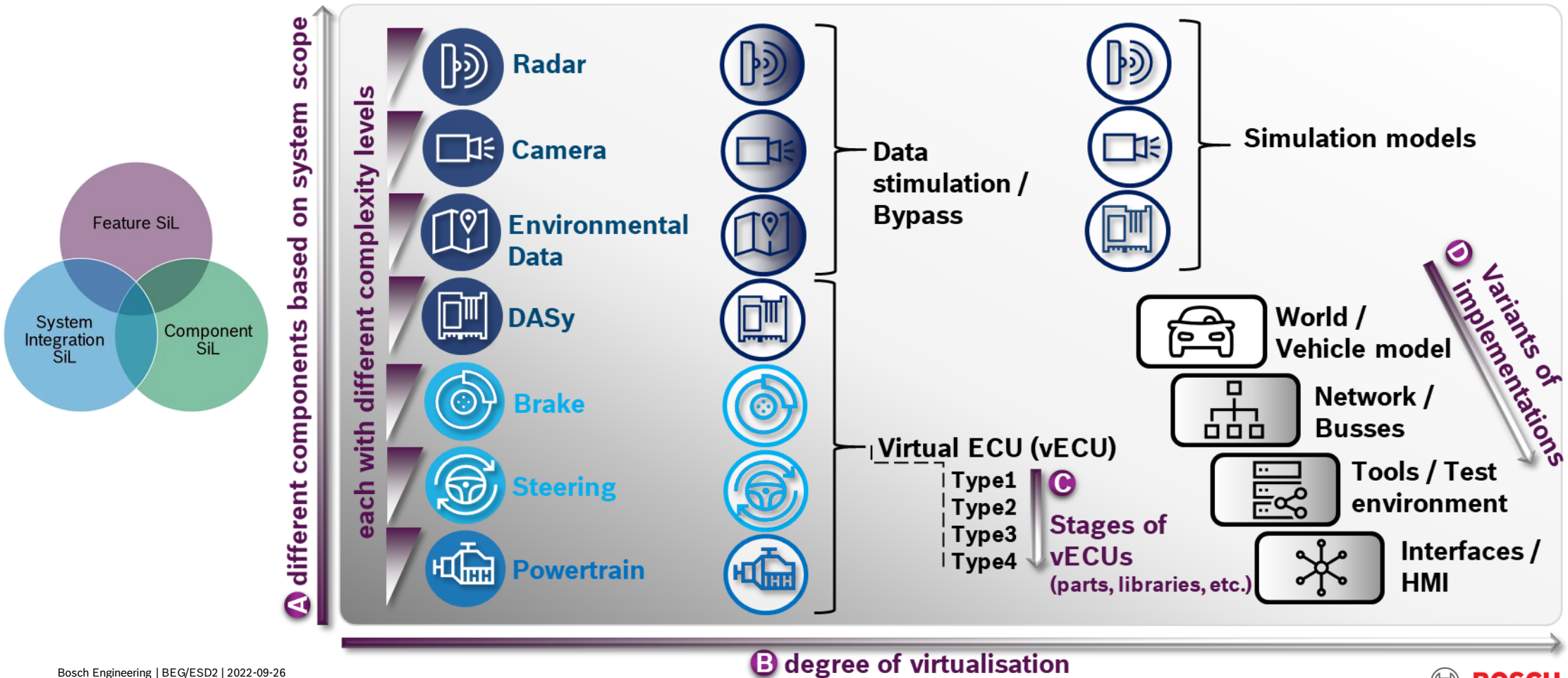


Validation & verification of safety critical situations

Benefit: Decoupling development from vehicle availability and reduced time on track required to calibrate a feature

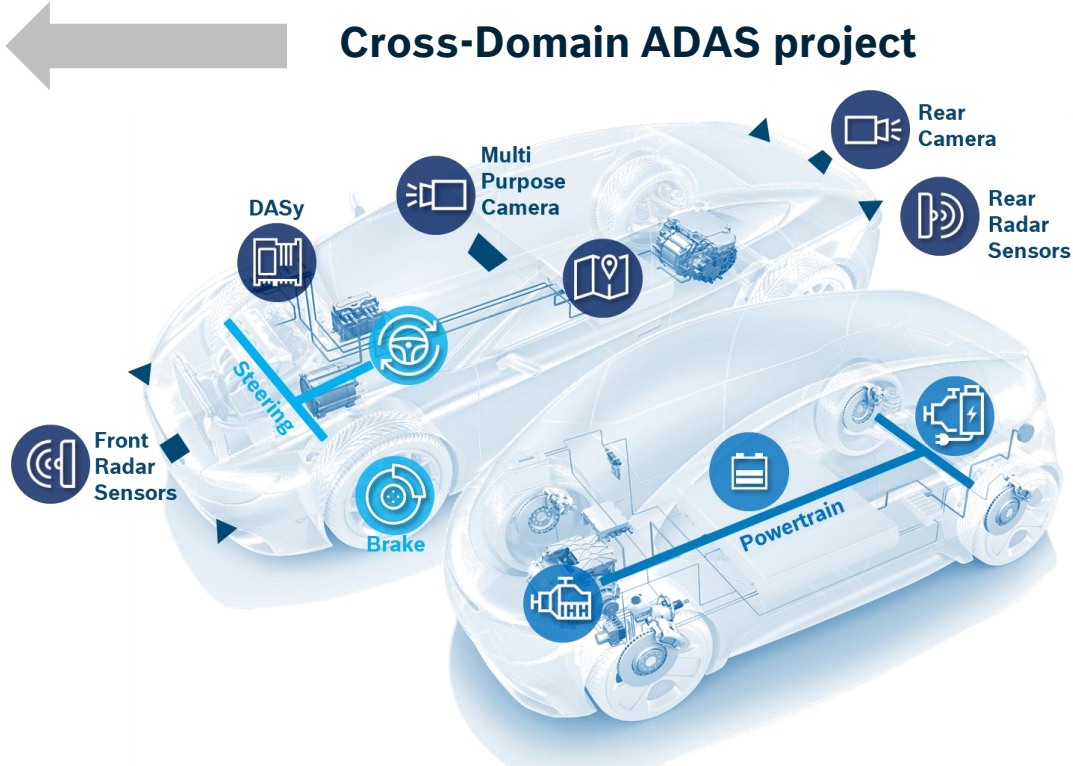
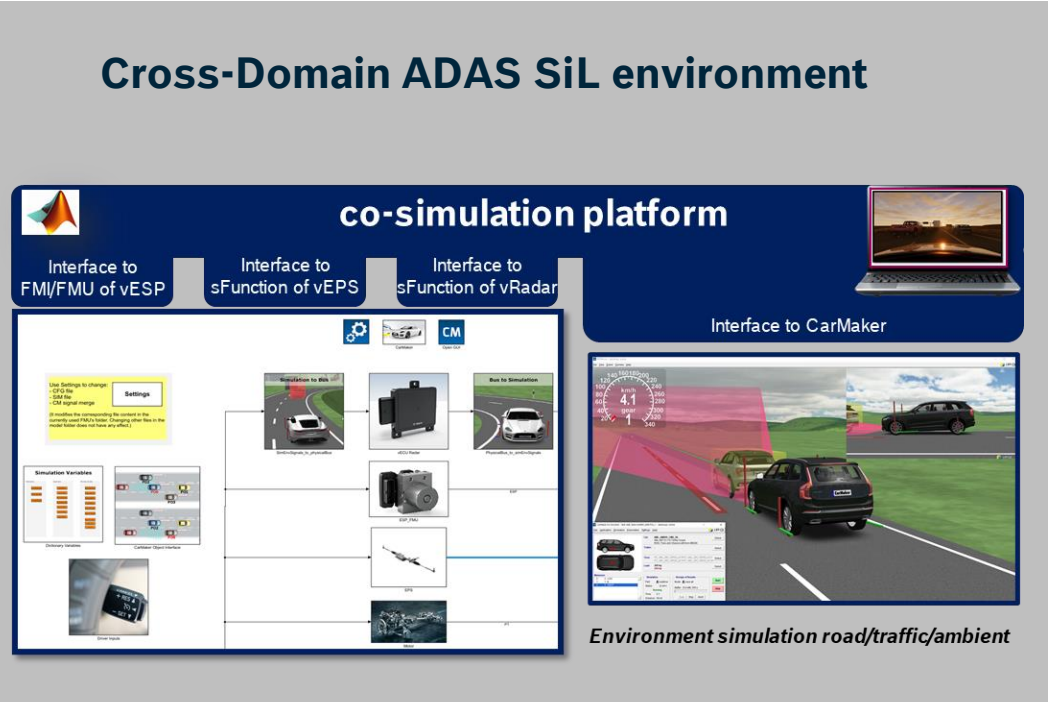
MATLAB/Simulink-based Cross-Domain SiL platform

Overview and context of SiL platform: ADAS complexity



MATLAB/Simulink-based Cross-Domain SiL platform

Overview and context of SiL platform

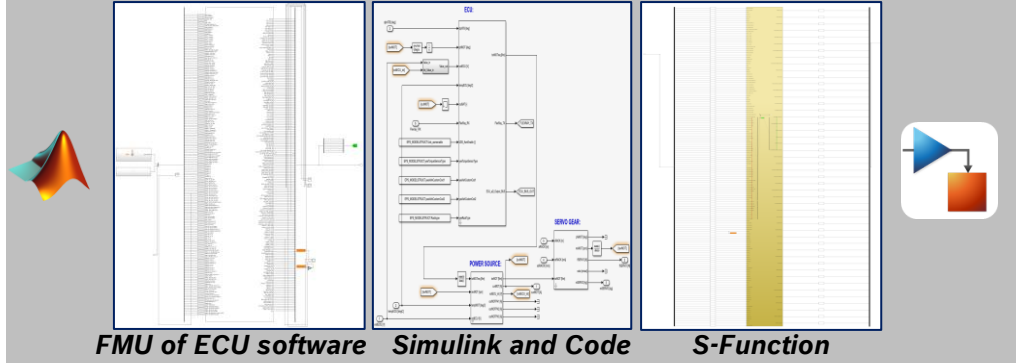


MathWorks provides necessary building blocks and interfaces to be used as a foundation for SiL platform

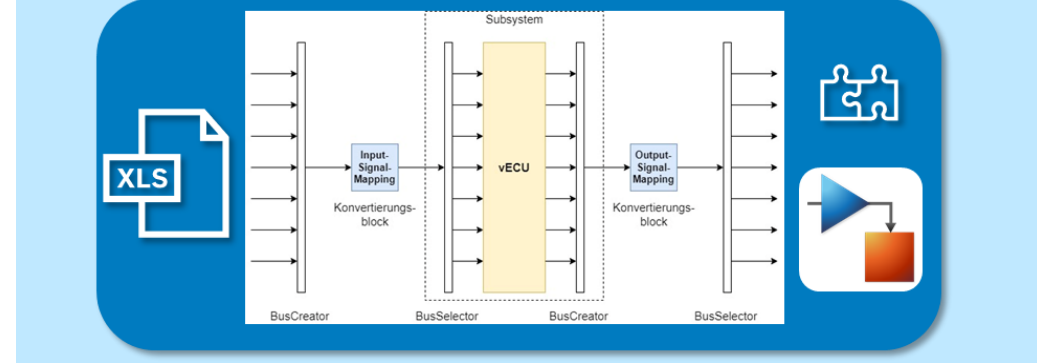
MATLAB/Simulink-based Cross-Domain SiL platform

MATLAB/Simulink-based tool chain

Creation of virtual ECUs (Radar, Camera)



Automated integration of SiL models



CDA - Tool for evaluation of measurements

The screenshot shows the CDA tool interface with several signal plots and a table of signal data. The plots include AEBWriting, AEBRate, EgoAccel, AEBAccelerations, EgoAcceleration, DistanceToTarget, RadarRange, and RadarRange.

Signal	Min	Max	Average	Standard Deviation	Number of points
AEBWriting	0	1	0.2	0.4	360
AEBRate	0	1	0.2	0.5	360
EgoAccel	0	49.8	30.5	20.2	360
AEBAccelerations	-14	14	3.3	10.3	360
EgoAcceleration	-0.5	1	-0.2	0.3	360
DistanceToTarget	0	10	5.5	0.8	360
RadarRange	0	64.2	20.9	18.8	360
RadarRange	-15.9	0.2	-6.4	6	360
RadarRange	0	0	0	0	360

Additional labels: d97, blf, asc, mat, mf4, incadat.

PEAS – Tool for automated simulations

The screenshot shows the PEAS tool interface with a table of test execution results:

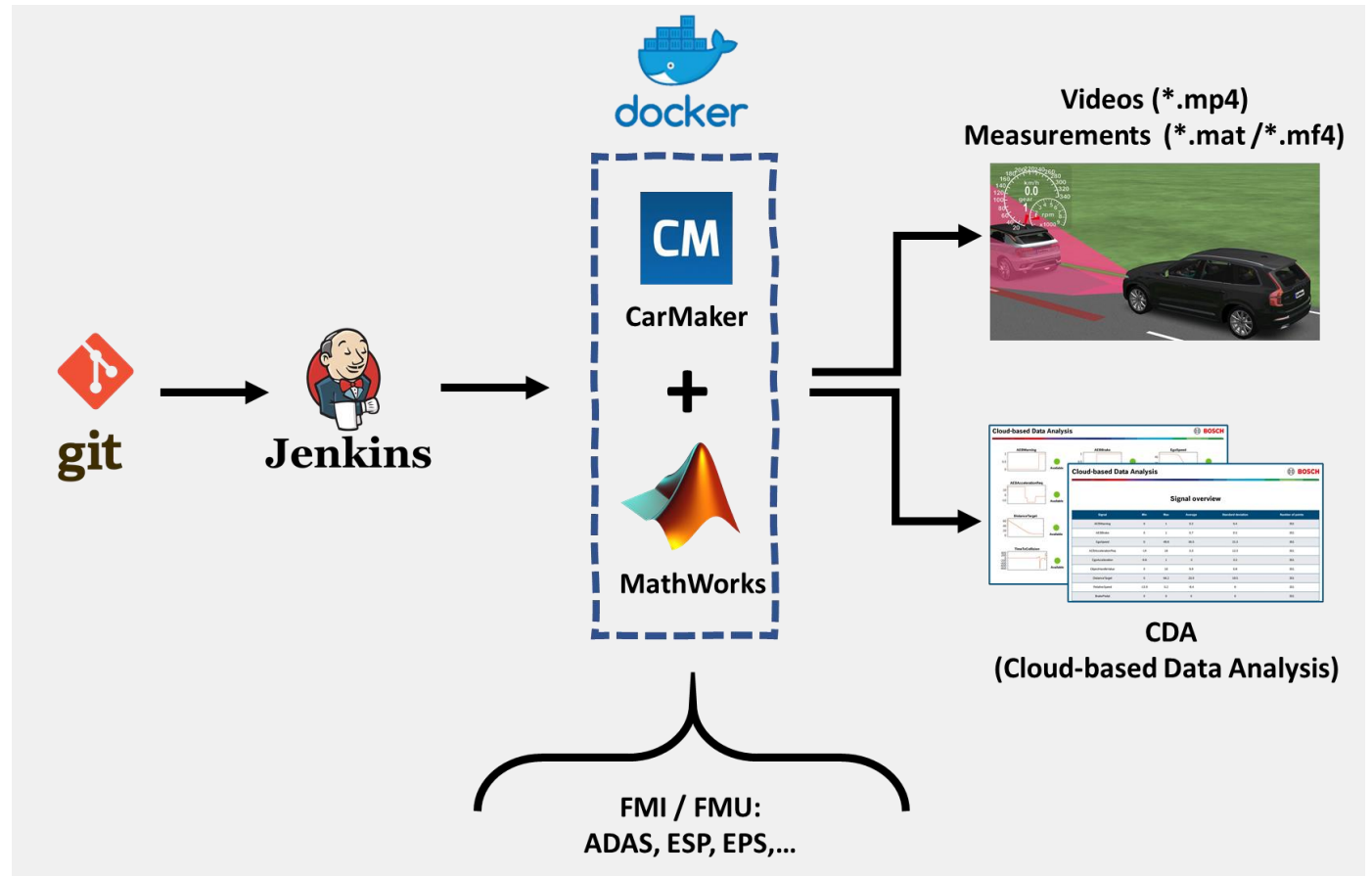
Test Case Name	Status	Ego Speed Start	Ego Speed end	TTC Start	Min AEBReq	Intervention Duration	Distance To Target Object	Imp
AER_50_0_w_DriverBrakes	Passed	0	0.28125	-250.2066	-14	3.799	5.91593	0.01
AER_50_0_w_DriverBrakes	Passed	0.18875	0	-610.9480	-14	4.599	5.20382	0.01
AER_50_20_w_DriverBrakes	Passed	0	1.1813	6.60952	-14	4.46	10.7261	1.41
AER_50_50_TTC	Passed	0.18875	0.28125	4.635683	-14	3.999	6.91420	1.81
AER_50_50_TTC	Failed	-	-	-	-14	3.199	4.83786	0.11
AER_60_20_w_DriverBrakes	Passed	15.4125	6.975	7.481381	-14	2.139	8.17481	1.01
0L_FSS_30_15	Failed	-	-	-	-	-	-	-
07_FSS_50_50	Failed	-	-	-	-	-	-	-

MATLAB/Simulink-based Cross-Domain SiL platform

MATLAB/Simulink-based tool chain: CI/CT context

Continuous Integration and Testing of project-specific virtual ECUs:

- ▶ Container constructs with docker for Cross-Domain SiL platform
- ▶ Integration in Jenkins
- ▶ Automated execution of test scenarios implemented in CarMaker
- ▶ Data storage
- ▶ Automated feature-specific evaluation in CDA (Bosch tool)
- ▶ Creation of reports



MATLAB/Simulink-based Cross-Domain SiL platform

Vehicle simulator: Feature demonstrator and training platform



Facts & Features

- Ideal for concept validations
- No physical prototypes needed
- Extensive, real-world ADAS function libraries
- Realistic sound reproduction

01

Define system conditions

Different libraries for vehicle types, Tracks, Bosch features and sounds

02

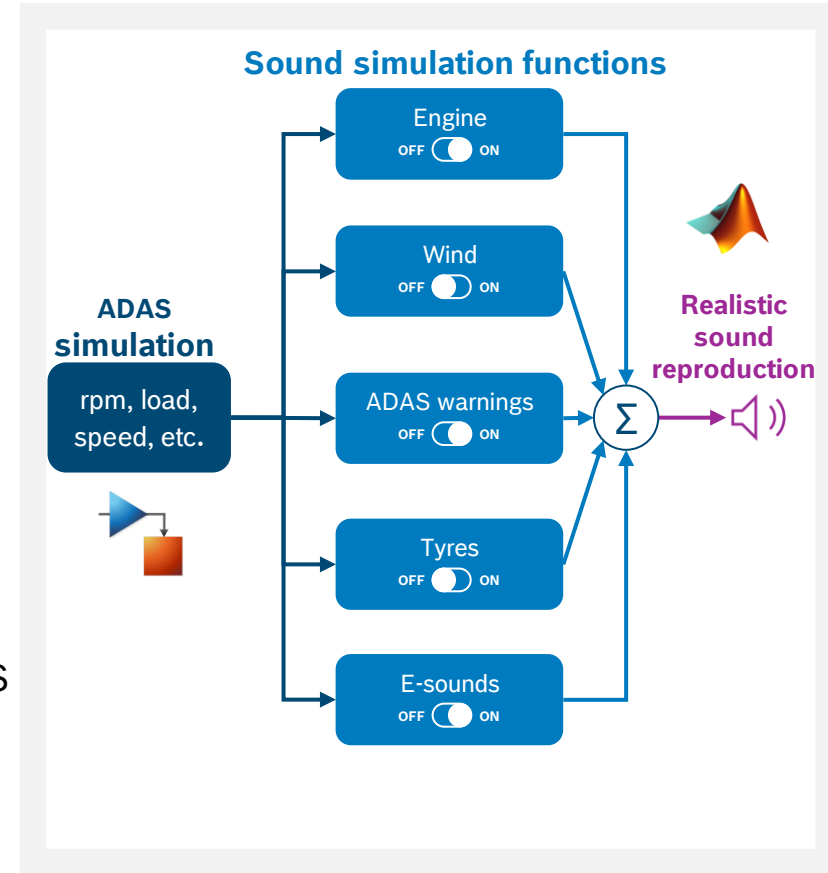
Real-time acoustic feedback

Drive your vehicle inside your virtual environment and have a full immersive ADAS experience

03

Develop faster

Execute pre-validations in your ADAS software functions and evaluate your sound design strategies



MATLAB/Simulink-based Cross-Domain SiL platform

Conclusion

Bosch Engineering provides an innovative digital engineering Software in the Loop (SiL) approach for the virtualization of ADAS features and continuous testing

MATLAB/Simulink environment is used for test-driven design, application and V&V strategy

SiL environment can be extended for vehicle driving simulator and sound simulation

ADAS feature can be evaluated and calibrated in cross-domain simulation environment

Automated tool chain for test execution and evaluation was developed with MathWorks products

THANK YOU



LET'S STAY IN TOUCH



Dr.-Ing. Irina Kaiser

Expert for Simulation in ADAS projects

Engineering Comfort and Safety Functions (BEG/ESD2)

Bosch Engineering GmbH

Tel. +49 7062 911-9226 | Mobile +49 152 54918916

Irina.Kaiser@de.bosch.com