



Developing world class electric vehicle solutions purpose-built for short & medium haul transportation in India & emerging markets

On a mission to catalyze carbon free transportation, by developing world class electric vehicles, purpose-built for India & emerging markets

WHY?

- ✓ Annually there are 10 mn air quality related deaths globally
- ✓ 39 of the 50 most polluted cities globally are in India

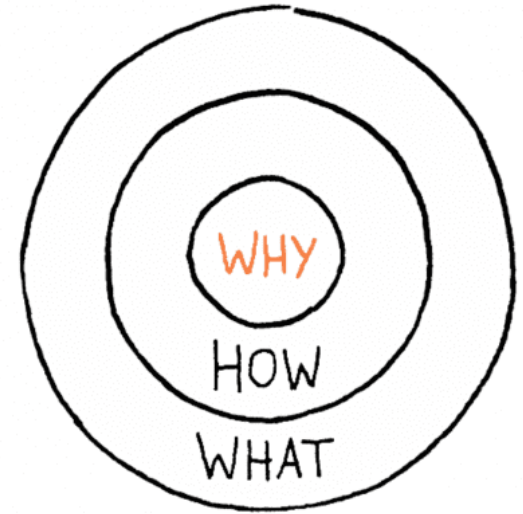
HOW?

- ✓ Engineering first approach
- ✓ Building EV technology in India in addition to “Make in India”

WHAT?

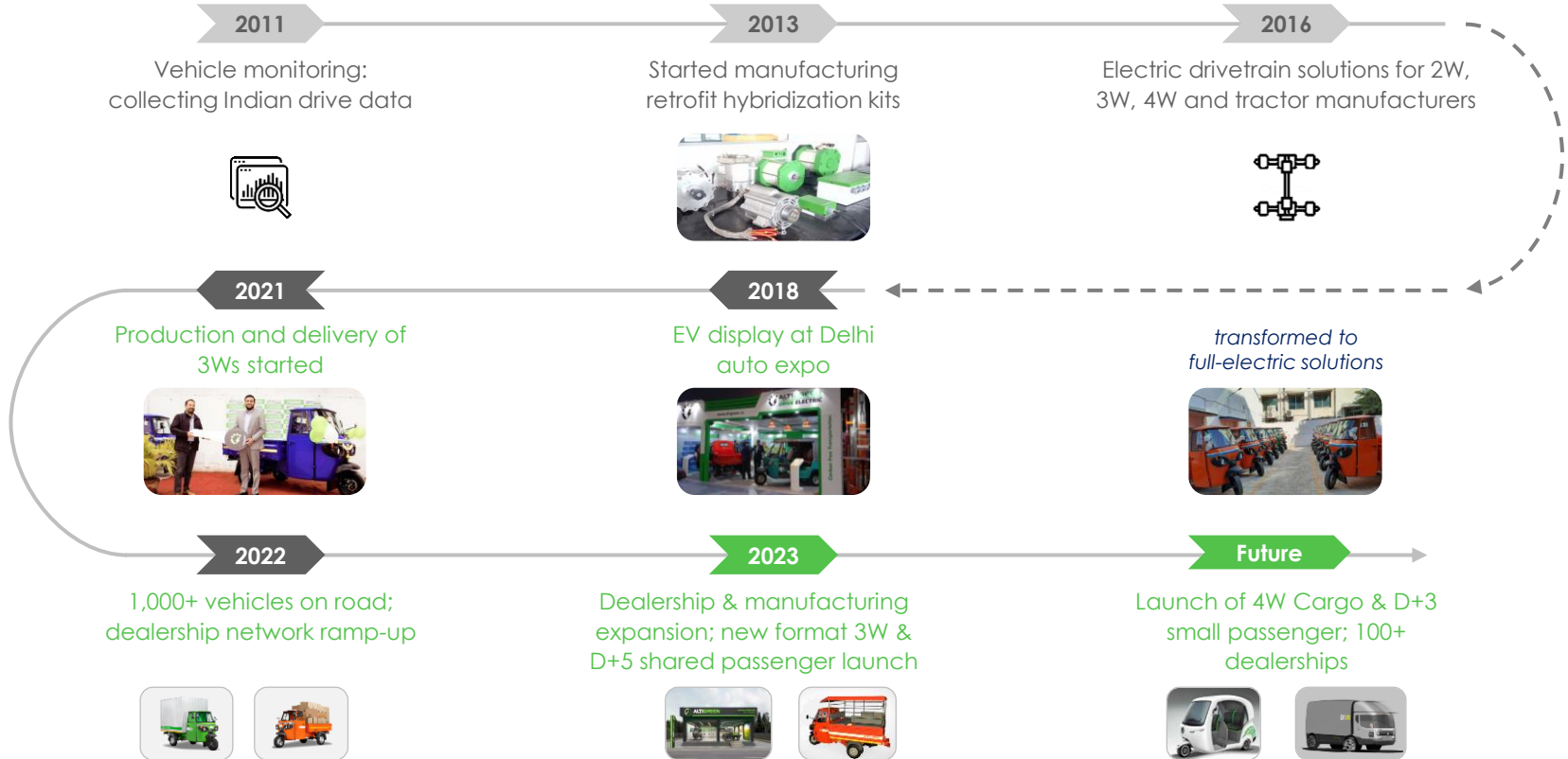
- ✓ Addressing the global need of EV transition by making 3W/4W in cargo and passenger mobility applications
- ✓ Targeting short and medium haul transportation in emerging markets

The Golden Circle



By Simon Sinek

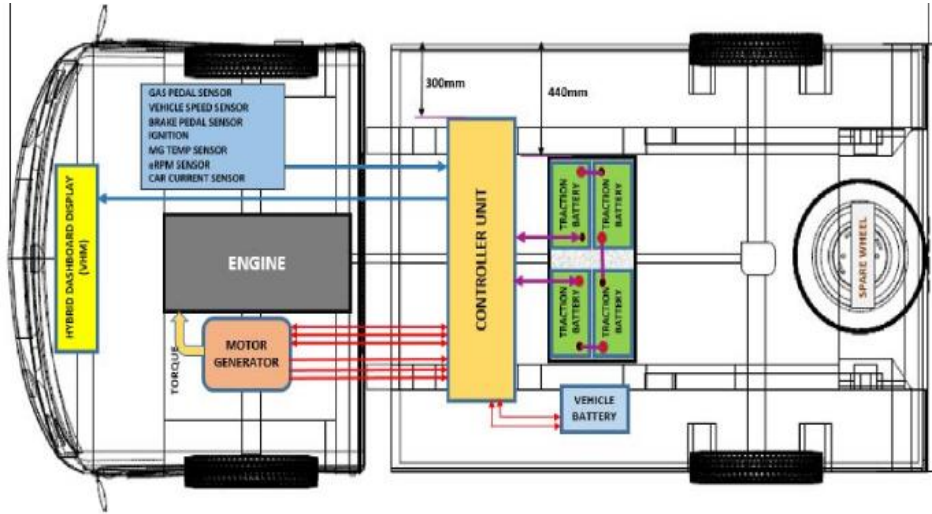
With 10+ years of R&D journey and a well-established technology platform, Altigreen is on track to expand its product portfolio and grow exponentially



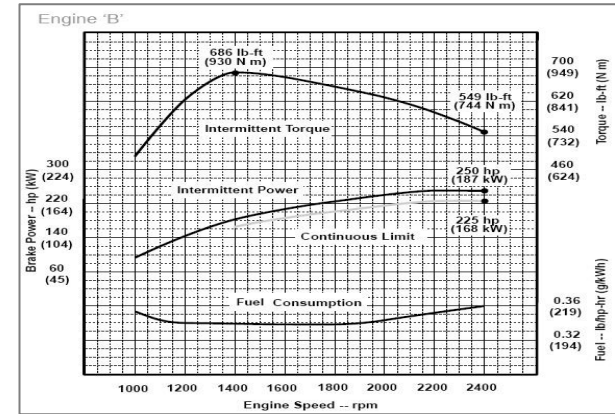
Overall Challenges

- ✓ Working with limited resources
- ✓ Shorter time to market for the Products
- ✓ Scarcity of skilled manpower for implementing complex algorithms
- ✓ Need for combined knowledge of Systems as well as target level implementation
- ✓ An architecture in place, for the software to be person independent
- ✓ Need of strong Testing and Validation process integrated with development
- ✓ EV Components to be EMI-EMC compliant
- ✓ Data analysis methods to improve on the systems
- ✓ Making products with price point suitable for Indian market without compromising on quality

Retrofit electric hybridization technology for ICE vehicles



Hybrid Retrofit Kit Layout

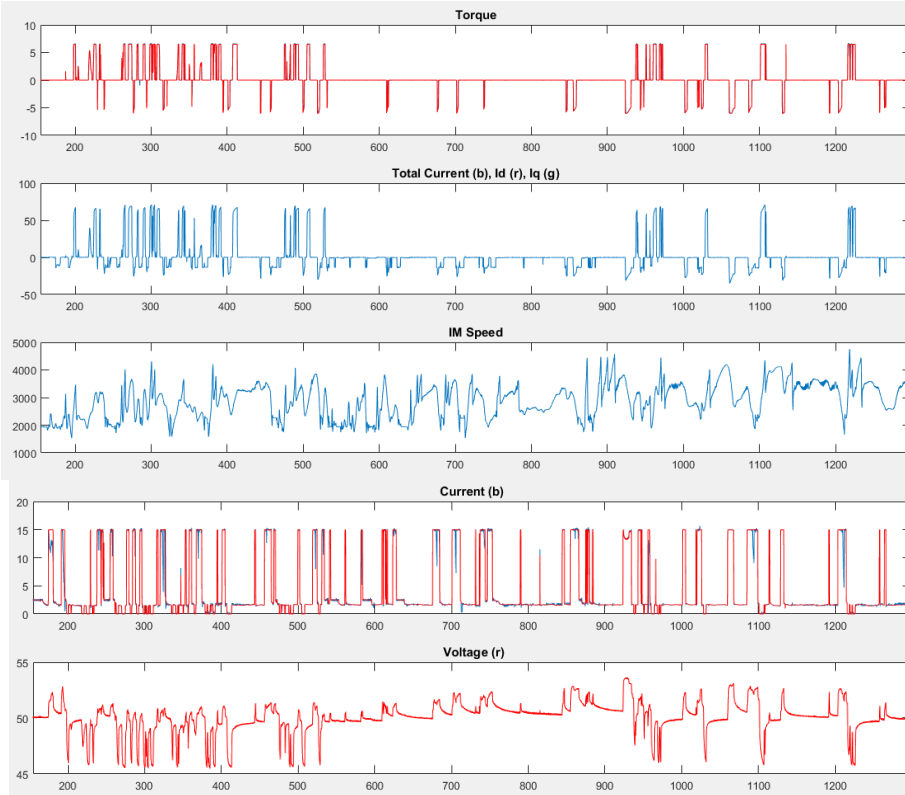


Engine Map Example

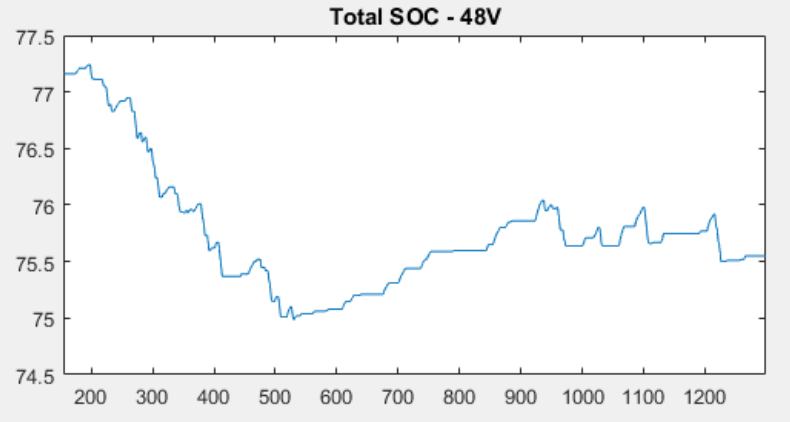
MATLAB used for Development, Simulation and Data Analysis

- ✓ Simulation models with engine map and hybrid powertrain
- ✓ Optimum Pulley ratio
- ✓ Optimum Assist-Regen schemes
- ✓ Data plots and drive summary analysis
- ✓ Production code generation using Embedded Coder

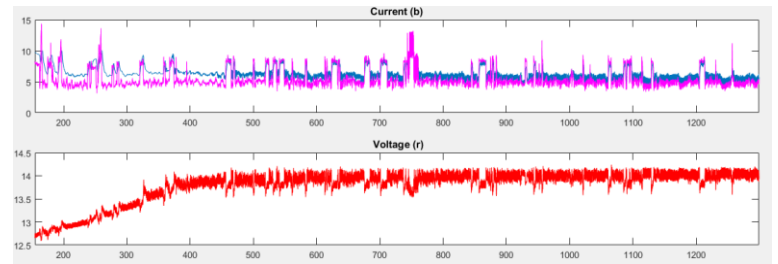
Hybrid System Data Set



IM – PMG parameters



48V battery



12V Vehicle battery

Full Electric Drivetrain Components Development

- ✓ Motor
- ✓ Motor Controller
- ✓ Gear Box
- ✓ DC-DC Converter
- ✓ Display Cluster
- ✓ BMS and Battery
- ✓ Telematics
- ✓ WebApp for telematics
Data collection

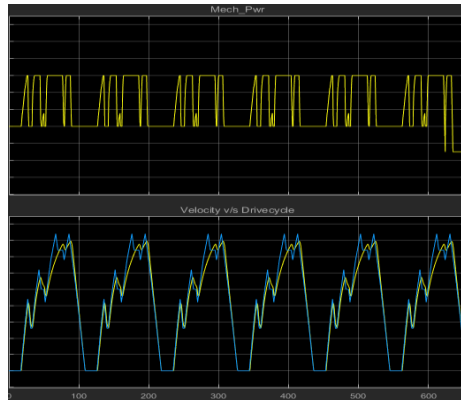
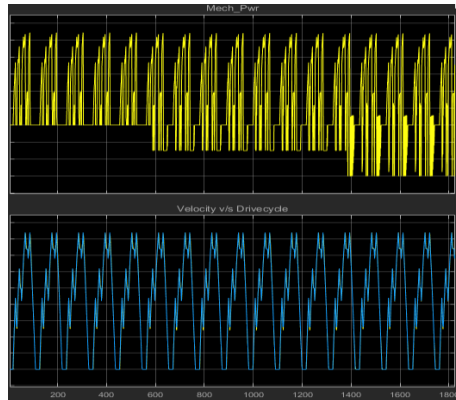
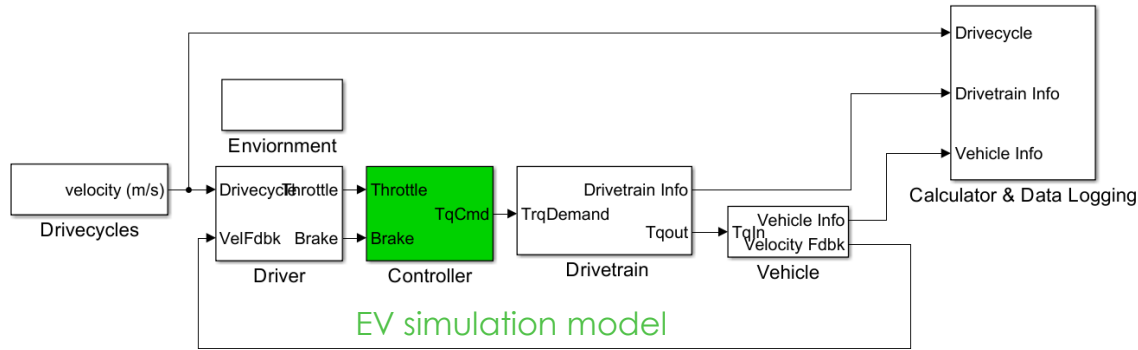


EV Drivetrain Layout

Requirements for Electric Vehicle design

- ✓ Vehicle to be comparable to ICE variant in terms of performance
- ✓ **Gradeability** in degrees
- ✓ **Kerb and GVW** in Kgs
- ✓ **Acceleration / Deceleration** in m/s^2
- ✓ **Maximum Speed** in km/h
- ✓ **Energy Consumption** in wh/kms
- ✓ **Range** in kms

Electric Vehicle Simulation Model



Motor Power and Vehicle Speed plots

Vehicle:

- ✓ Speed Profile
- ✓ Vehicle Mass
- ✓ Wheel Radius
- ✓ Gear Ratio
- ✓ Gradient
- ✓ Vehicle Dynamics parameters

Battery:

- ✓ SOC
- ✓ Capacity
- ✓ Voltage

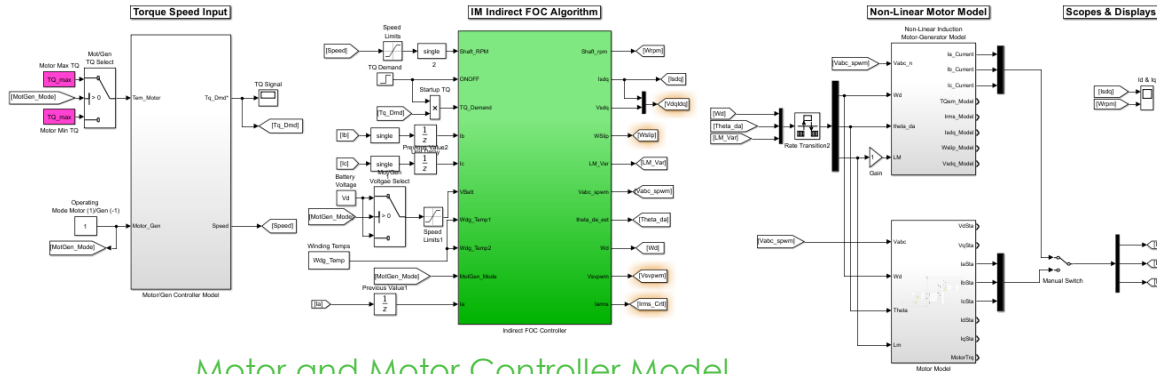
Motor & Controller:

- ✓ Efficiency Maps
- ✓ Peak/Continuous Torque
- ✓ Peak/Continuous Power
- ✓ Peak Time
- ✓ Max Speed

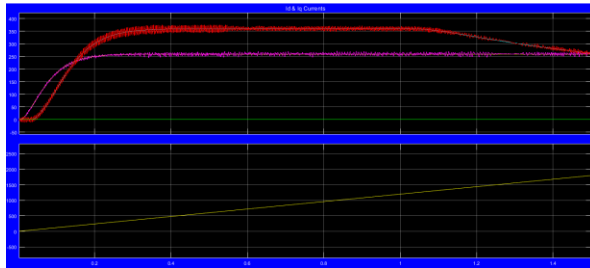
Motor Controls Requirements

- ✓ Mathematical model of Induction Motor
- ✓ Field Oriented Controls implementation
- ✓ Target deployment of FOC
- ✓ Matching the controller timings to target executions
- ✓ Combine the Vehicle controller with Motor controller on the embedded target

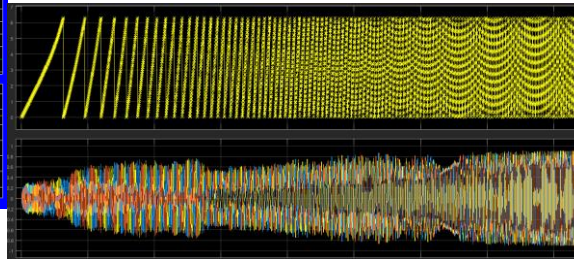
Motor Controls Simulation



Motor and Motor Controller Model



I_d - I_q currents and Speed



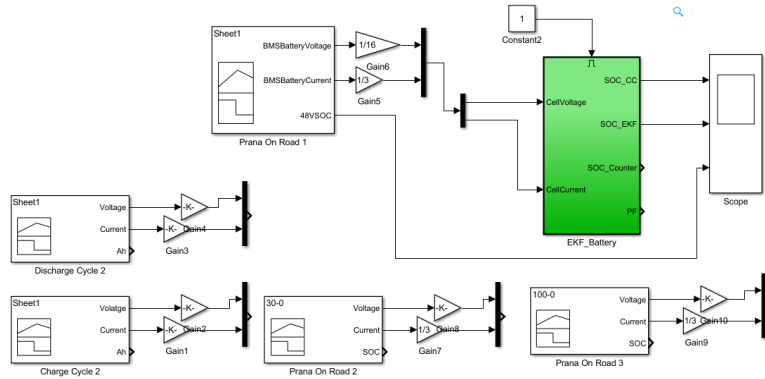
Theta and Modulation Index

- ✓ Torque Speed Profiles as inputs
- ✓ Motor model
- ✓ Motor Controller algorithm - FOC
- ✓ Blocks in the FOC module are for the embedded target code generation
- ✓ FOC execution timings are adjusted so that they are matching to embedded target

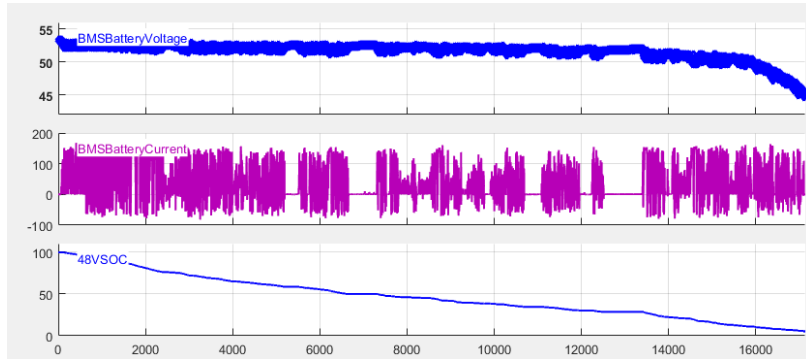
BMS Requirements

- ✓ Integrating device drivers Manual code and model-based algorithms
- ✓ Filtering of signals for EMI compliance
- ✓ Unit Testable Modules
- ✓ Target Deployment of BMS
- ✓ Better SOC Estimate to avoid Range Anxiety

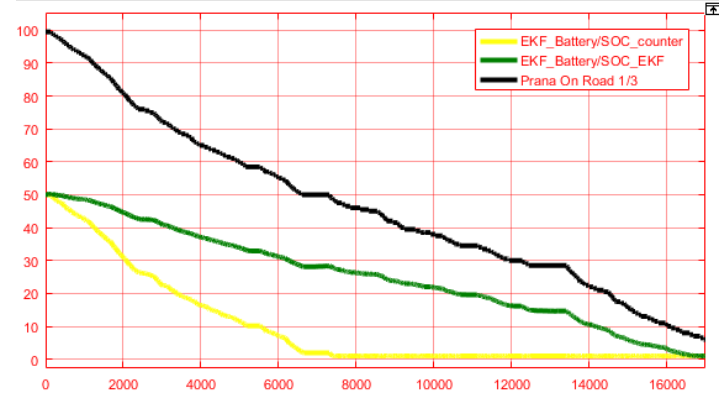
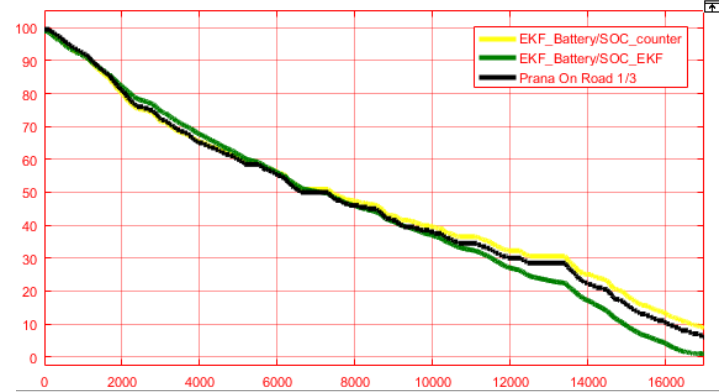
SOC Estimation using Kalman Filter for BMS



SOC Estimation by EKF



Real World discharge data with CC SOC



Better SOC estimate with Kalman with gradual correction

Software Deployment using Simulink and Embedded Coder

- ✓ Vehicle Controller and Motor Controller in a single Physical Controller
- ✓ Upto 90% model based development leaving a small % for hand coding
- ✓ Manual/hand code is integrated in the models and the hex files generated by building the models
- ✓ Modeling to Simulation to Code generation to target deployment time significantly reduced
- ✓ Quick iterations between simulations to target deployment and using the real-world data back for simulations for any parameters tuning

State-of-the-art greenfield manufacturing facility in Bengaluru and Brand Centers across 30+ Indian cities



Altigreen's Manufacturing Plant, near Bengaluru



Altigreen Brand Centre

Altigreen 3W Electric Cargo Vehicles



Altigreen neEV



Altigreen neEV - Tez

Thank You

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